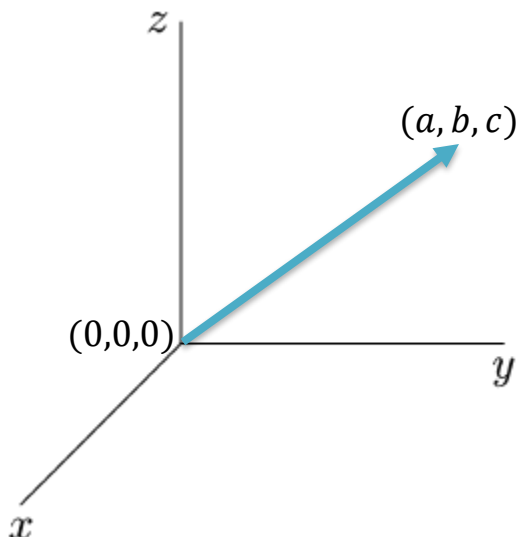


A Quick Review of a few topics from 3rd Semester Calculus

1. Vectors in R^3

A vector in R^3 is a line segment from the origin $(0,0,0)$ to a point in R^3 , (a,b,c) . We denote this vector by $\langle a,b,c \rangle$.



We can also write this vector as:

$$\langle a,b,c \rangle = a\vec{i} + b\vec{j} + c\vec{k};$$

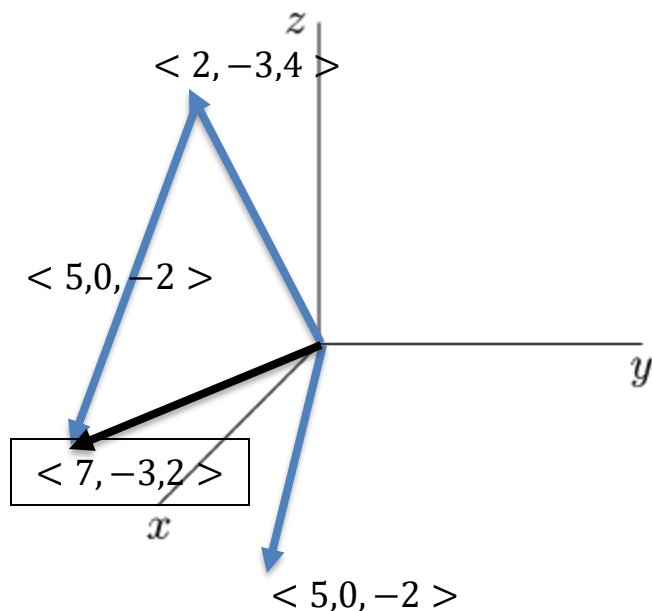
where $\vec{i} = \langle 1,0,0 \rangle$, $\vec{j} = \langle 0,1,0 \rangle$, $\vec{k} = \langle 0,0,1 \rangle$.

$$\text{Ex. } \langle 2,5,-1 \rangle = 2\vec{i} + 5\vec{j} - \vec{k}.$$

We can add or subtract vectors by adding or subtracting their components.

$$\text{Ex. } \langle 2,-3,4 \rangle + \langle 5,0,-2 \rangle = \langle 7,-3,2 \rangle$$

$$\langle 3,2,-4 \rangle - \langle 5,-1,2 \rangle = \langle -2,3,-6 \rangle$$



We can also multiply a vector by a real number (called a scalar), by multiplying each of the components.

Ex. $(-6) \langle 3, -2, -3 \rangle = \langle -18, 12, 18 \rangle$

There are 2 ways to multiply vectors in R^3 , through a "Dot" product (whose answer is a number, not a vector), and through a "Cross" product (whose answer is a vector not a number).

Let $\vec{v}_1 = \langle a_1, b_1, c_1 \rangle$ and $\vec{v}_2 = \langle a_2, b_2, c_2 \rangle$

Dot Product:

$$\vec{v}_1 \cdot \vec{v}_2 = a_1 a_2 + b_1 b_2 + c_1 c_2$$

Note: $\vec{v}_1 \cdot \vec{v}_2$ is a real number, NOT a vector.

Ex. $\langle 2, -3, 4 \rangle \cdot \langle 5, 0, -2 \rangle = (2)(5) + (-3)(0) + (4)(-2) = 10 + 0 - 8 = 2.$

Notice that: $\vec{v}_1 \cdot \vec{v}_1 = a_1^2 + b_1^2 + c_1^2 = \|\vec{v}_1\|^2$

$$\text{or } \|\vec{v}_1\| = \sqrt{\vec{v}_1 \cdot \vec{v}_1} = \sqrt{a_1^2 + b_1^2 + c_1^2}$$

Properties of Dot product:

1. $\vec{v}_1 \cdot \vec{v}_2 = \vec{v}_2 \cdot \vec{v}_1$
2. $\vec{v}_1 \cdot (\vec{v}_2 + \vec{v}_3) = \vec{v}_1 \cdot \vec{v}_2 + \vec{v}_1 \cdot \vec{v}_3$

If $\vec{v} = a\vec{i} + b\vec{j} + c\vec{k}$, then a unit vector (a vector of length 1) in the direction of $\vec{v}$ is given by:

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = \frac{a}{\sqrt{a^2+b^2+c^2}}\vec{i} + \frac{b}{\sqrt{a^2+b^2+c^2}}\vec{j} + \frac{c}{\sqrt{a^2+b^2+c^2}}\vec{k}$$

Ex. Find a unit vector in the direction of $\vec{v} = \langle 2, -2, 1 \rangle = 2\vec{i} - 2\vec{j} + \vec{k}$

Here $a = 2$, $b = -2$, $c = 1$, so $a^2 + b^2 + c^2 = 4 + 4 + 1 = 9$.

$$\vec{u} = \frac{a}{\sqrt{a^2+b^2+c^2}}\vec{i} + \frac{b}{\sqrt{a^2+b^2+c^2}}\vec{j} + \frac{c}{\sqrt{a^2+b^2+c^2}}\vec{k} = \frac{2}{3}\vec{i} - \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}$$

Theorem: Assume $\vec{v}, \vec{w} \neq \vec{0}$. Then $\vec{v} \cdot \vec{w} = 0$ if and only if $\vec{v}$ and $\vec{w}$ are perpendicular.

Cross Product:

$$\vec{v}_1 = \langle a_1, b_1, c_1 \rangle = a_1\vec{i} + b_1\vec{j} + c_1\vec{k}$$

$$\vec{v}_2 = \langle a_2, b_2, c_2 \rangle = a_2\vec{i} + b_2\vec{j} + c_2\vec{k}$$

$$\vec{v}_1 \times \vec{v}_2 = \det \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} \quad (\text{Note: The "det" is often omitted})$$

Ex. Find $\langle 2, 1, -3 \rangle \times \langle -1, 1, 2 \rangle$

$$\begin{aligned} \langle 2, 1, -3 \rangle \times \langle -1, 1, 2 \rangle &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2 & 1 & -3 \\ -1 & 1 & 2 \end{vmatrix} \\ &= \begin{vmatrix} 1 & -3 \\ -1 & 2 \end{vmatrix} \vec{i} - \begin{vmatrix} 2 & -3 \\ -1 & 2 \end{vmatrix} \vec{j} + \begin{vmatrix} 2 & 1 \\ -1 & 1 \end{vmatrix} \vec{k} \\ &= [(1)(2) - (-1)(-3)]\vec{i} - [(2)(2) - (-1)(-3)]\vec{j} + [(2)(1) - (-1)(1)]\vec{k} \\ &= 5\vec{i} - \vec{j} + 3\vec{k} \end{aligned}$$

Notice that the answer is a vector, NOT a number (ie a scalar).

Properties:

1. $\vec{v} \times \vec{w}$ is perpendicular to $\vec{v}$ and $\vec{w}$ (hence perpendicular to the plane containing $\vec{v}$ and $\vec{w}$)
2. $\vec{v} \times \vec{w} = 0$ if and only if $\vec{v}$ and $\vec{w}$ are parallel or $\vec{v} = 0$ or $\vec{w} = 0$.
3. $\vec{v} \times \vec{w} = -\vec{w} \times \vec{v}$

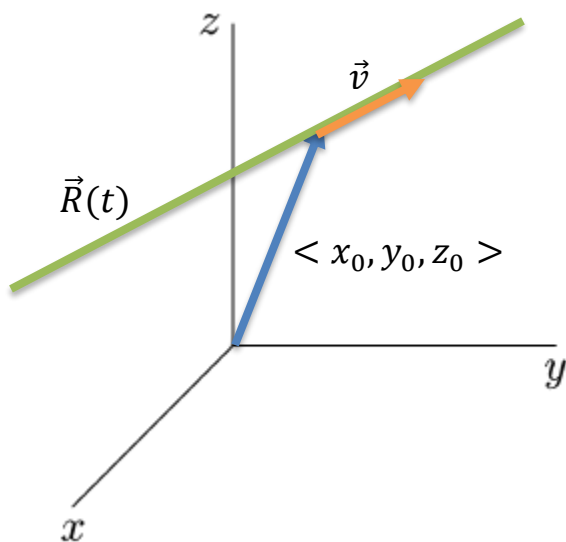
2. Finding an equation of a line in R^3

Given a point (x_0, y_0, z_0) and a direction vector $\vec{v} = \langle a, b, c \rangle$, we can write a vector equation of a line through (x_0, y_0, z_0) in the direction of $\vec{v} = \langle a, b, c \rangle$ by:

$$\vec{R}(t) = \langle x_0, y_0, z_0 \rangle + t\vec{v} = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle$$

Which can also be written as:

$$\vec{R}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle \quad (\text{Vector form of line})$$



This line can also be written in parametric form:

$$x = x_0 + at$$

$$y = y_0 + bt$$

$$z = z_0 + ct$$

Ex. Find a vector equation and parametric equations for the line through the points $P = (2, -3, -1)$ and $Q = (-1, 2, 3)$.

First we find a direction vector from P to Q (or from Q to P)

$$\begin{aligned}\text{Direction Vector } \vec{v} = \overrightarrow{PQ} &= \langle -1 - 2, 2 - (-3), 3 - (-1) \rangle \\ &= \langle -3, 5, 4 \rangle\end{aligned}$$

Now we use either point, say, $(2, -3, -1) = (x_0, y_0, z_0)$:

$$\vec{R}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle = \langle 2 - 3t, -3 + 5t, -1 + 4t \rangle$$

In parametric equations this becomes:

$$x = x_0 + at = 2 - 3t$$

$$y = y_0 + at = -3 + 5t$$

$$z = z_0 + at = -1 + 4t.$$

Equations of line segments from P to Q .

If we find an equation of the line through the points P and Q by finding the direction vector $\vec{v} = \overrightarrow{PQ} = \langle a, b, c \rangle = \vec{Q} - \vec{P}$, and use the starting point

$P = (x_0, y_0, z_0)$ as our point on the line then the vector equation of the line is

$$\vec{R}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle; \quad t \in \mathbb{R}.$$

If the equation of the line through P and Q is found this way (there are an infinite number of equations of lines that go through P and Q) then the line segment from P to Q is given by

$$\vec{R}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle; \quad 0 \leq t \leq 1.$$

Notice that at $t = 0$; $\vec{R}(0) = \langle x_0, y_0, z_0 \rangle = P$

$$t = 1; \quad \vec{R}(1) = \langle x_0 + a, y_0 + b, z_0 + c \rangle = Q$$

since $\vec{v} = \overrightarrow{PQ} = \vec{Q} - \vec{P}$.

Alternatively, we can find a line segment from P to Q by taking:

$$\vec{R}(t) = t\vec{P} + (1 - t)\vec{Q}; \quad 0 \leq t \leq 1.$$

Ex. Find an equation for the line segment between $P = (2, -3, -1)$ and $Q = (-1, 2, 3)$.

In the previous example we found an equation of the line through P and Q by finding the direction $\vec{v} = \overrightarrow{PQ} = \langle a, b, c \rangle = \vec{Q} - \vec{P}$, and using the starting point $P = (2, -3, -1)$. Thus an equation for the line segment between P and Q is

$$\vec{R}(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle = \langle 2 - 3t, -3 + 5t, -1 + 4t \rangle; \quad 0 \leq t \leq 1.$$

Using the second approach we could find an equation for the line segment by

$$\begin{aligned} \vec{R}(t) &= t\vec{P} + (1 - t)\vec{Q} = t \langle 2, -3, -1 \rangle + (1 - t) \langle -1, 2, 3 \rangle; \quad 0 \leq t \leq 1. \\ &= \langle 2 - 3t, -3 + 5t, -1 + 4t \rangle; \quad 0 \leq t \leq 1. \end{aligned}$$

3. Equations of planes in R^3

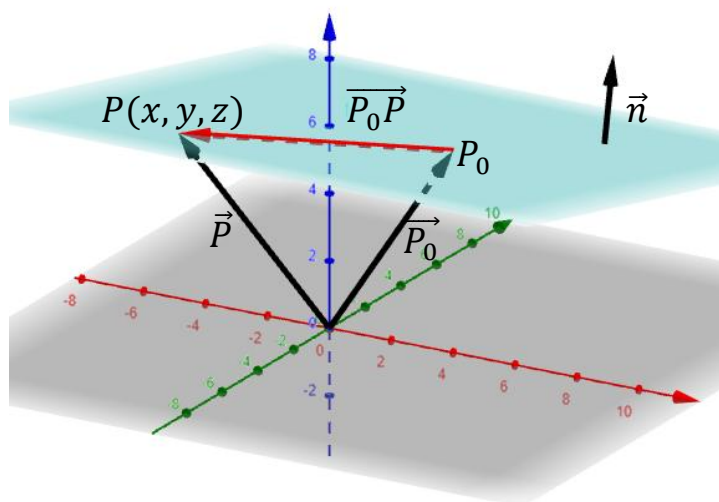
In order to write an equation for a plane in R^3 we need a point (x_0, y_0, z_0) and a vector, $\vec{n}$, perpendicular to the plane, called a "normal" vector.

For any general point (x, y, z) on the plane we have:

$$\vec{P} = \langle x, y, z \rangle, \quad \vec{P}_0 = \langle x_0, y_0, z_0 \rangle, \quad \vec{n} = \langle A, B, C \rangle,$$

$$\vec{n} \cdot \overrightarrow{P_0P} = \vec{n} \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$$

$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0.$$



Ex. Find an equation of a plane containing the points

$$A(2,1,1), B(0,4,1), C(-2,1,4).$$

$$\overrightarrow{AB} = \langle 0 - 2, 4 - 1, 1 - 1 \rangle = \langle -2, 3, 0 \rangle$$

$$\overrightarrow{AC} = \langle -2 - 2, 1 - 1, 4 - 1 \rangle = \langle -4, 0, 3 \rangle$$

$\overrightarrow{AB}$ and $\overrightarrow{AC}$ are vectors that lie in the plane containing $A(2,1,1), B(0,4,1), C(-2,1,4)$.

How do we find a vector, $\vec{n}$, perpendicular to the plane containing A, B, C ?

$$\begin{aligned}
\vec{n} = \overrightarrow{AB} \times \overrightarrow{AC} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -2 & 3 & 0 \\ -4 & 0 & 3 \end{vmatrix} \\
&= \begin{vmatrix} 3 & 0 \\ 0 & 3 \end{vmatrix} \vec{i} - \begin{vmatrix} -2 & 0 \\ -4 & 3 \end{vmatrix} \vec{j} + \begin{vmatrix} -2 & 3 \\ -4 & 0 \end{vmatrix} \vec{k} \\
&= 9\vec{i} - (-6)\vec{j} + (-(-12))\vec{k} = 9\vec{i} + 6\vec{j} + 12\vec{k}.
\end{aligned}$$

$$\vec{n} = \langle 9, 6, 12 \rangle = \langle A, B, C \rangle.$$

Using any point on the plane we can take $(x_0, y_0, z_0) = (2, 1, 1)$.

An equation of the plane: $A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$

$$9(x - 2) + 6(y - 1) + 12(z - 1) = 0;$$

$$\text{Or} \quad 9x + 6y + 12z - 36 = 0$$

$$\text{Or} \quad 3x + 2y + 4z = 12$$

4. Equations of Cylinders and a few common Quadric Surfaces in R^3

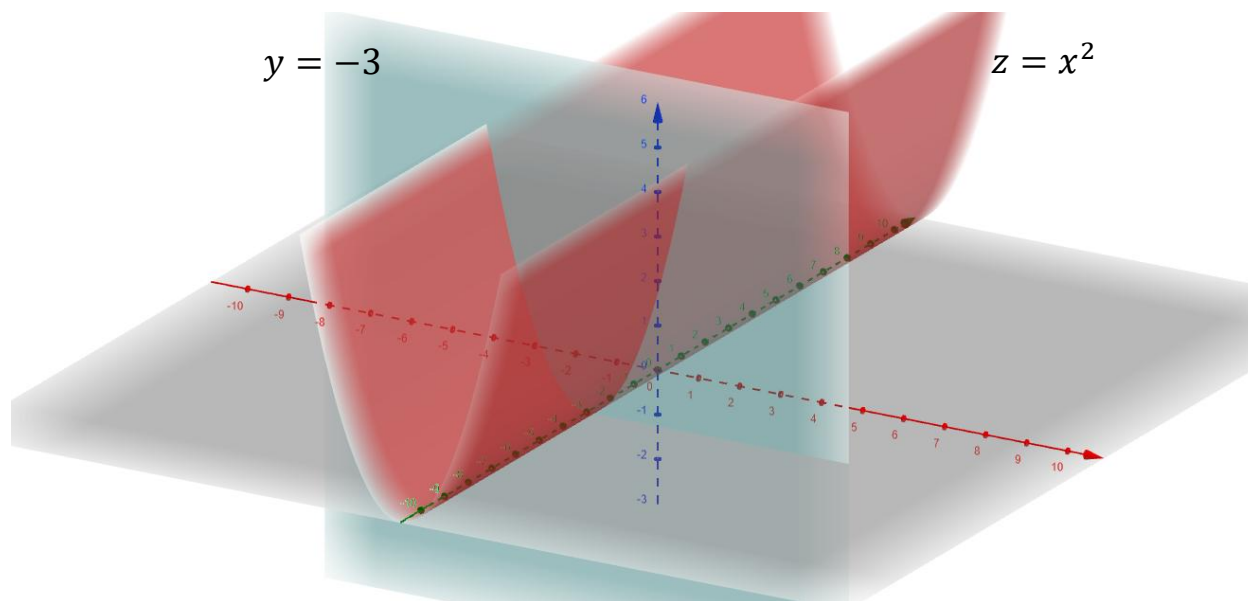
Def. A cylinder consists of all lines that are parallel to a given line and pass through a given plane curve.

Notice that if an equation in R^3 contains only 2 variables, the graph is a cylinder.

When picturing a graph of an equation in R^3 it is often helpful to examine the cross-sections of the graph. That is, what curve do we get when we cut the surface with a plane such as $z = \text{constant}$ or $y = \text{constant}$ or $x = \text{constant}$.

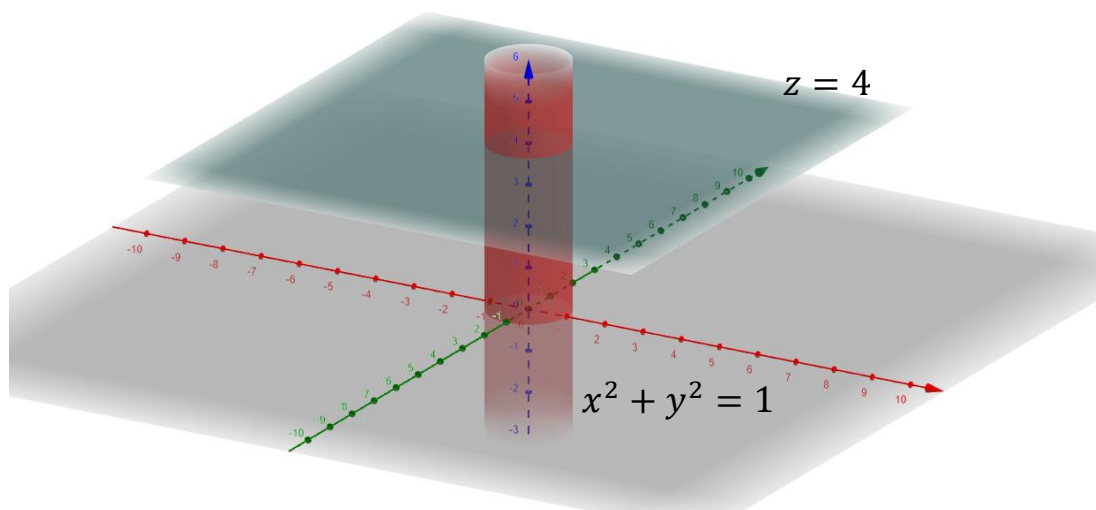
Ex. Sketch $z = x^2$ in $\mathbb{R}^3$

In the xz plane ($y = 0$) this is just the parabola $z = x^2$. Since the function does not have a "y" in it, every cross sectional of the plane $y = k$ is the same parabola. This is called a parabolic cylinder. In fact, if one of x, y, z is missing from the equation, then you will get a cylinder.

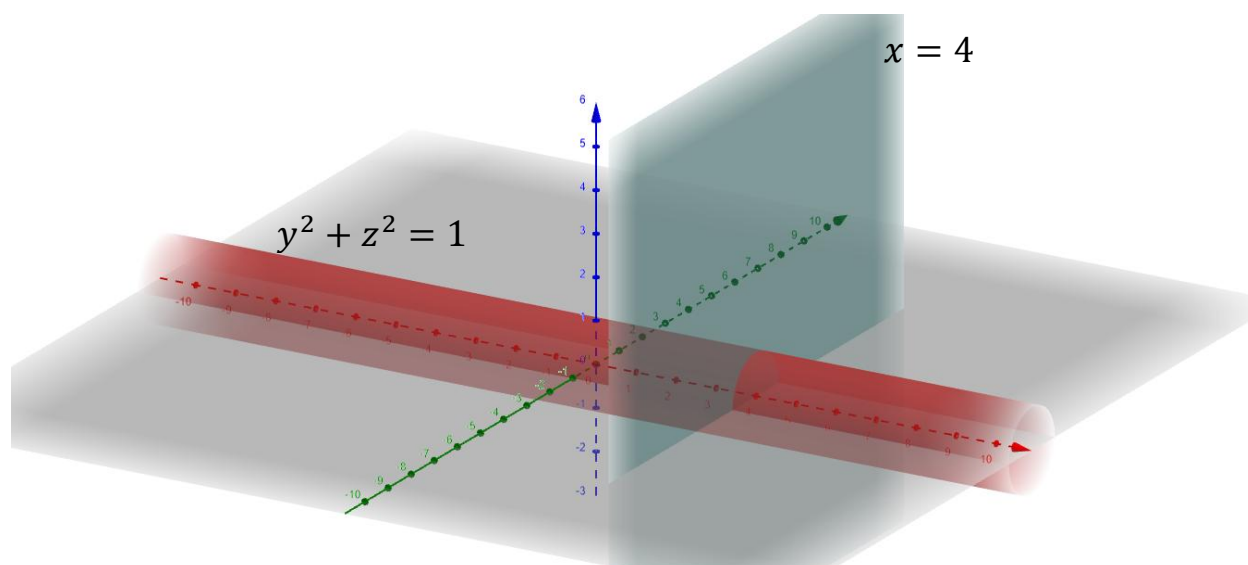


Ex. Sketch in $\mathbb{R}^3$: a) $x^2 + y^2 = 1$ b) $y^2 + z^2 = 1$

a) $x^2 + y^2 = 1$ is a circle of radius 1 in $z = k$ plane.



b) $y^2 + z^2 = 1$ is a circle of radius 1 in $x = k$ plane.



The graph of any equation of the form: $\frac{z^2}{a^2} = \frac{x^2}{b^2} + \frac{y^2}{c^2}$ is a cone.

Ex. sketch $z^2 = \frac{x^2}{2} + \frac{y^2}{3}$, using level curves and sections.

$$z = k: k^2 = \frac{x^2}{2} + \frac{y^2}{3}$$

slices $\parallel$ to xy plane are ellipses if $k \neq 0$

if $k = 0$, then it's a point

$$x = k: z^2 - \frac{y^2}{3} = \frac{k^2}{2}$$

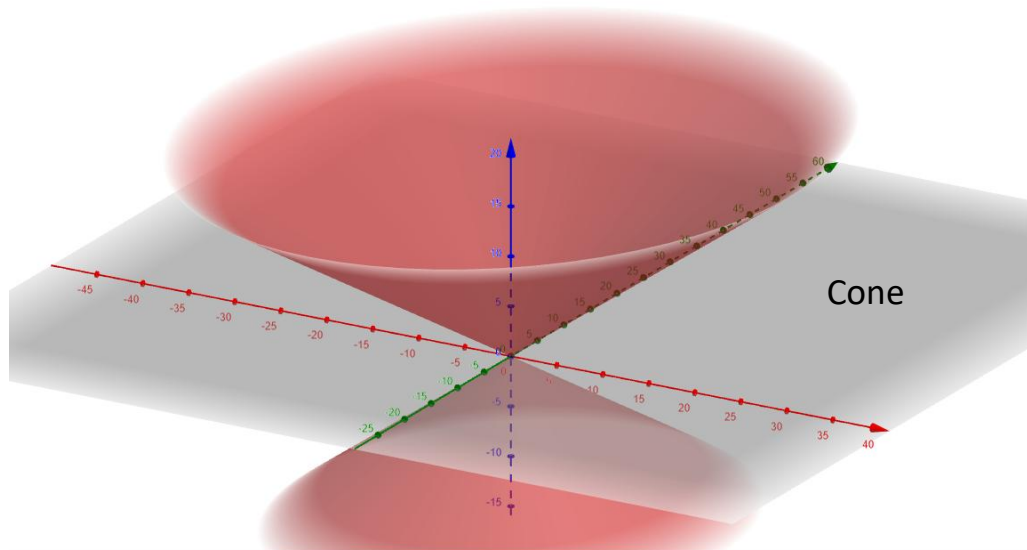
slices $\parallel$ to yz plane are hyperbolas if $k \neq 0$,

major axis is the z axis.

$$y = k: z^2 - \frac{x^2}{2} = \frac{k^2}{3}$$

slices $\parallel$ to xz plane are hyperbolas if $k \neq 0$,

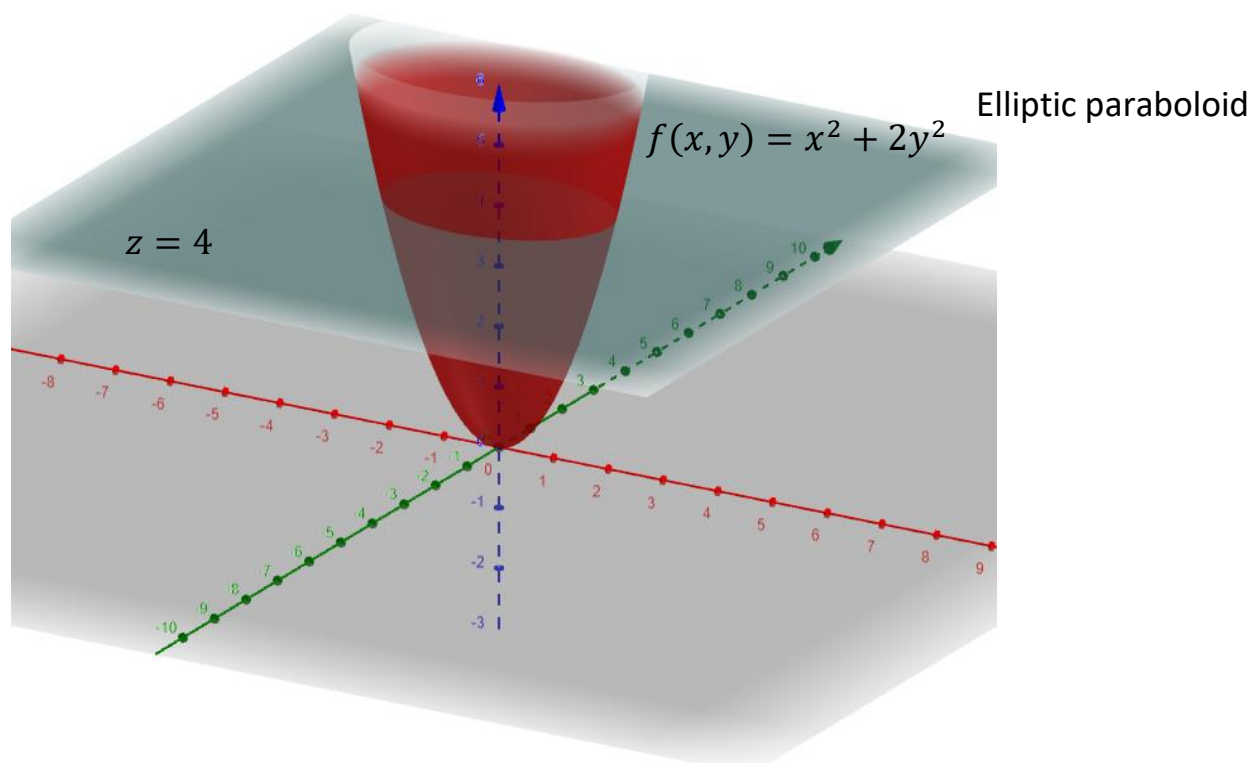
major axis is the z axis.



The graph of any equation of the form $\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ is an elliptic paraboloid.

Ex. Sketch $f(x, y) = x^2 + 2y^2$. Domain = $\mathbb{R}^2$; range $z \geq 0$.

Level curves for $z = k > 0$ are ellipses.



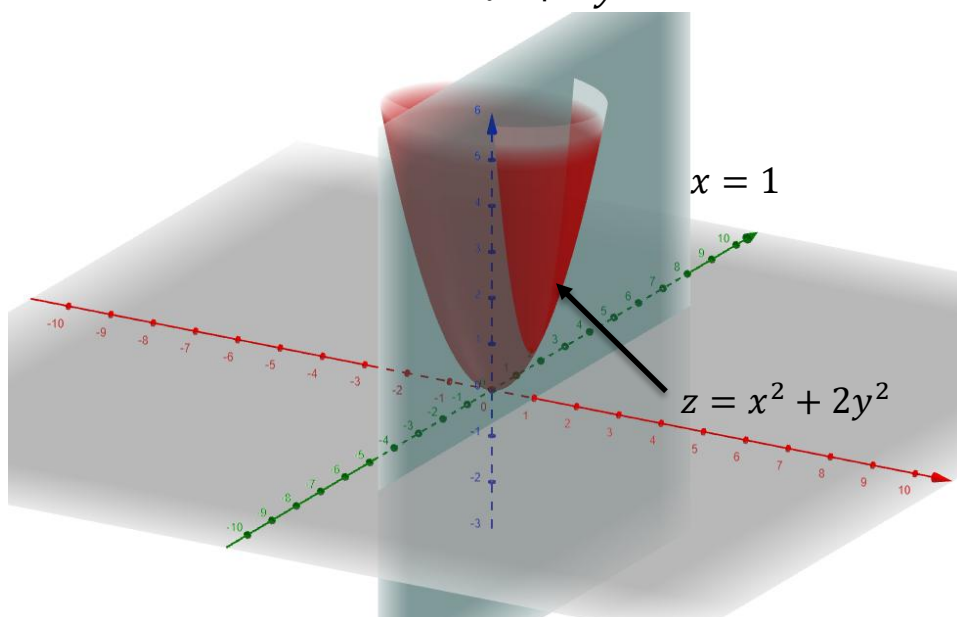
Sections of the graph of f are parabolas.

For example, if $y = k$, then we get:

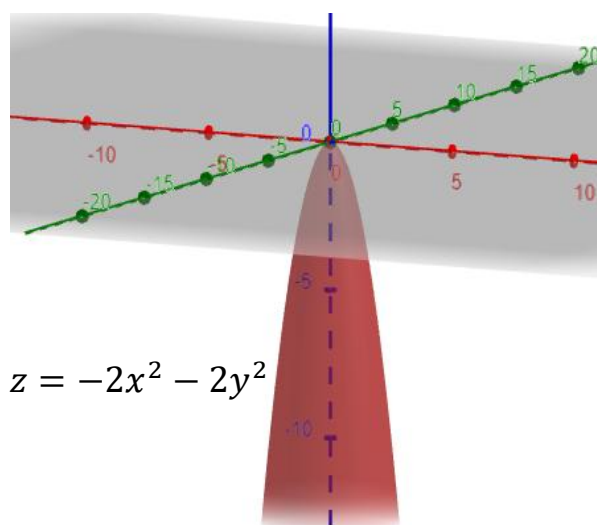
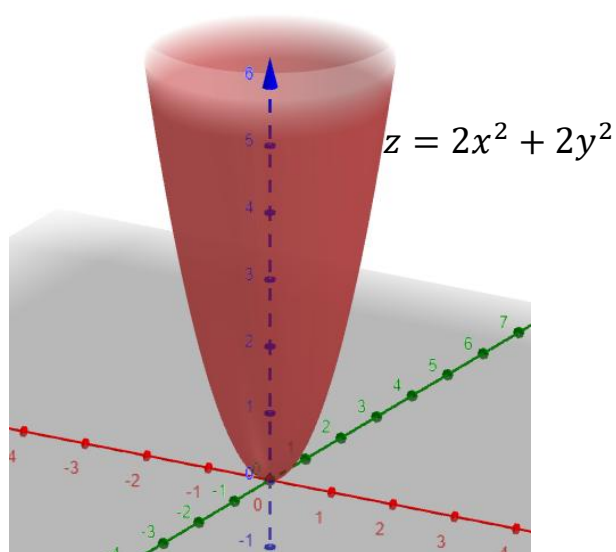
$$z = x^2 + 2k^2$$

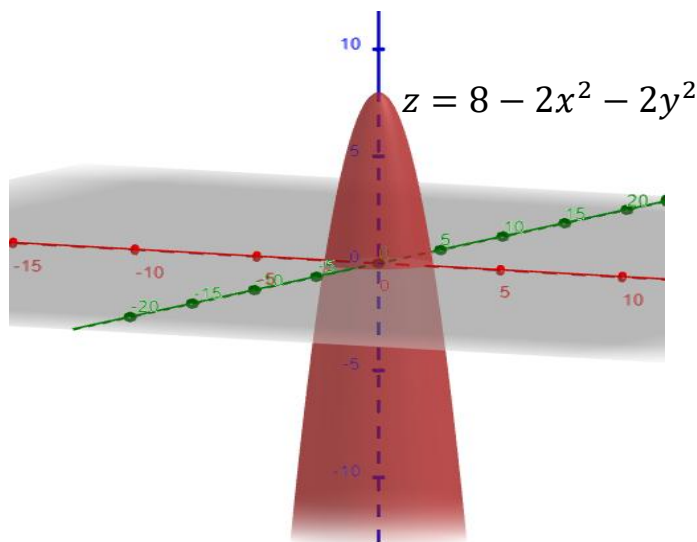
If $x = k$, then we get:

$$z = k^2 + 2y^2$$



Ex. Sketch a graph of $z = -2x^2 - 2y^2$ and $z = 8 - 2x^2 - 2y^2$.





The graph of any equation of the form $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ is an ellipsoid (when $a = b = c$ you get a sphere).

Ex. Use the level curves and sections to sketch $x^2 + \frac{y^2}{9} + \frac{z^2}{4} = 1$.

When $z = 0$: $x^2 + \frac{y^2}{9} = 1$

$z = k$: $x^2 + \frac{y^2}{9} + \frac{k^2}{4} = 1$

$x^2 + \frac{y^2}{9} = 1 - \frac{k^2}{4}$ is an ellipse if $-2 < k < 2$. As $k \rightarrow 2$

or -2 the major and minor axes are shrinking to 0. For example,

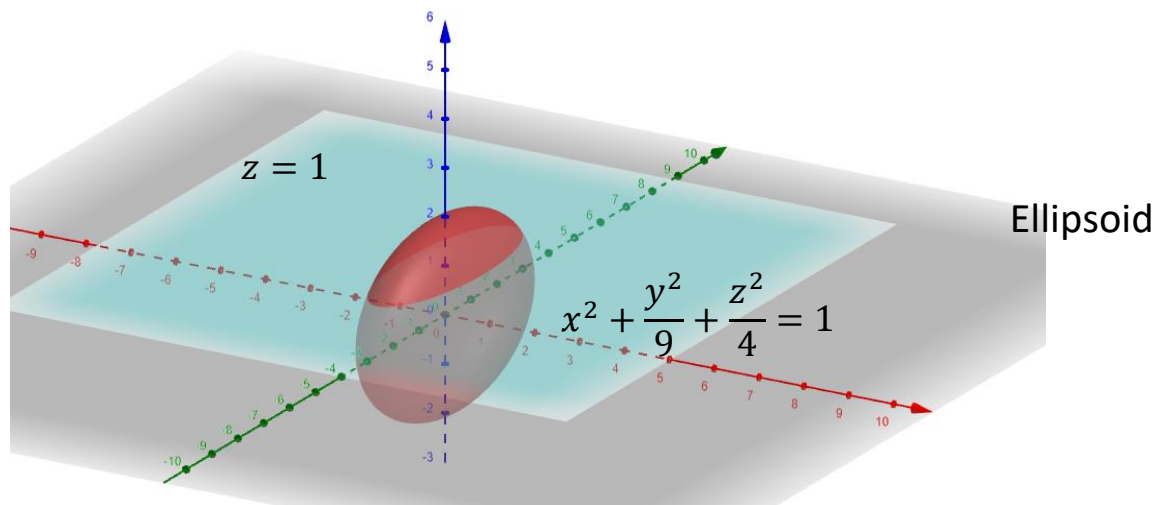
$k = 1$: $x^2 + \frac{y^2}{9} = \frac{3}{4} \Rightarrow \frac{x^2}{\frac{3}{4}} + \frac{y^2}{\frac{27}{4}} = 1$.

At $x = 0$: $\frac{y^2}{9} + \frac{z^2}{4} = 1$ ellipse in yz plane

At $x = k$: $\frac{y^2}{9} + \frac{z^2}{4} = 1 - k^2$ $-1 < k < 1$ ellipse

At $y = 0$: $x^2 + \frac{z^2}{4} = 1$ ellipse in the xz plane

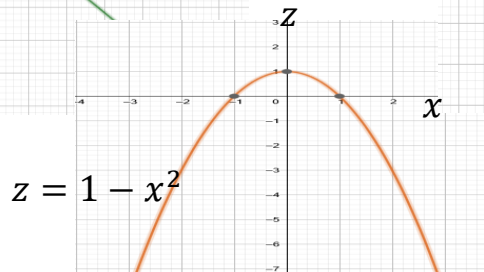
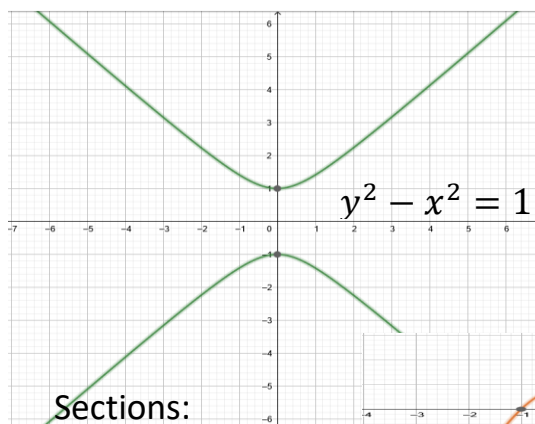
At $y = k$: $x^2 + \frac{z^2}{4} = 1 - \frac{k^2}{9}$ $-3 < k < 3$ ellipse



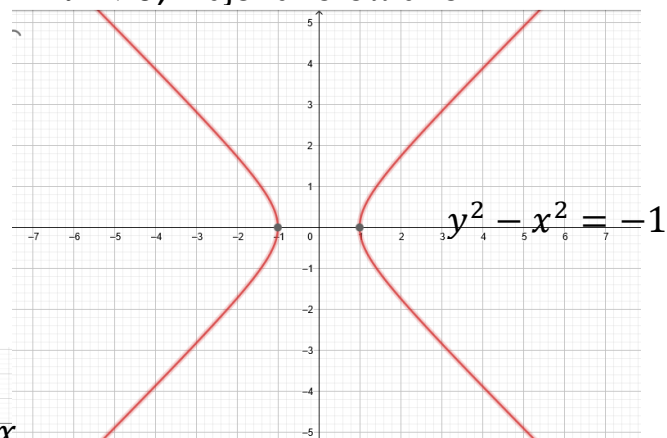
Ex. Use level curves and sections to sketch $z = y^2 - x^2$.

Level curves: $k = y^2 - x^2$:

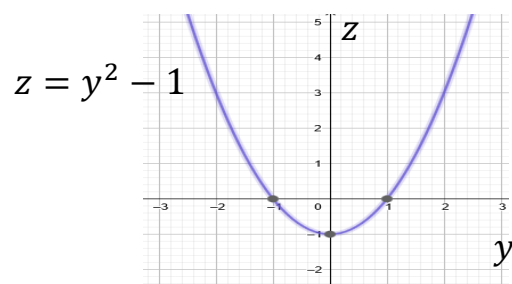
Hyperbolas, $k > 0$, major axis is y axis



$k < 0$, major axis is x axis.

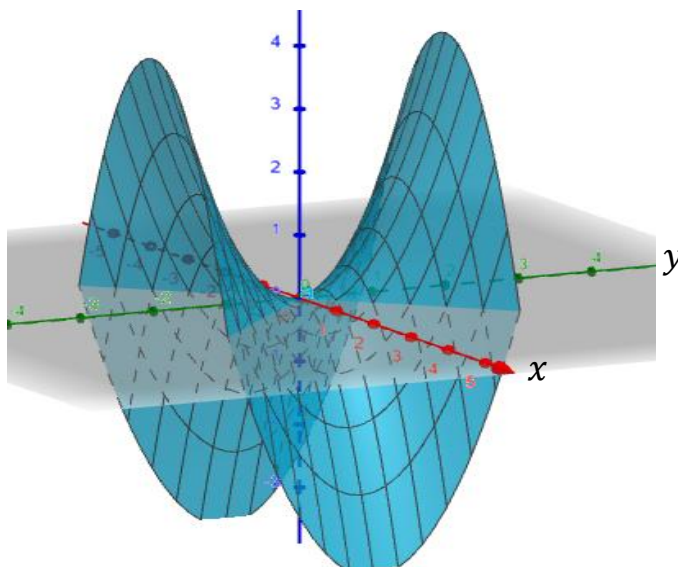


parabolas in xz plane opening
in negative z direction.



$x = k$; $z = y^2 - k^2$,
parabolas in yz plane opening
opening in positive z direction.

Hyperbolic Paraboloid (Saddle)



Ex. Sketch $\frac{x^2}{4} + y^2 - \frac{z^2}{4} = 1$, using level curves and sections.

At $z = k$: $\frac{x^2}{4} + y^2 = 1 + \frac{k^2}{4}$ ellipse in slices $\parallel xy$ plane

At $y = 0$: $\frac{x^2}{4} - \frac{z^2}{4} = 1$ hyperbola in slices $\parallel xz$ plane

At $y = k$: $\frac{x^2}{4} - \frac{z^2}{4} = 1 - k^2$, hyperbolas in xz plane if $k \neq \pm 1$

$-1 < k < 1$, major axis is x axis

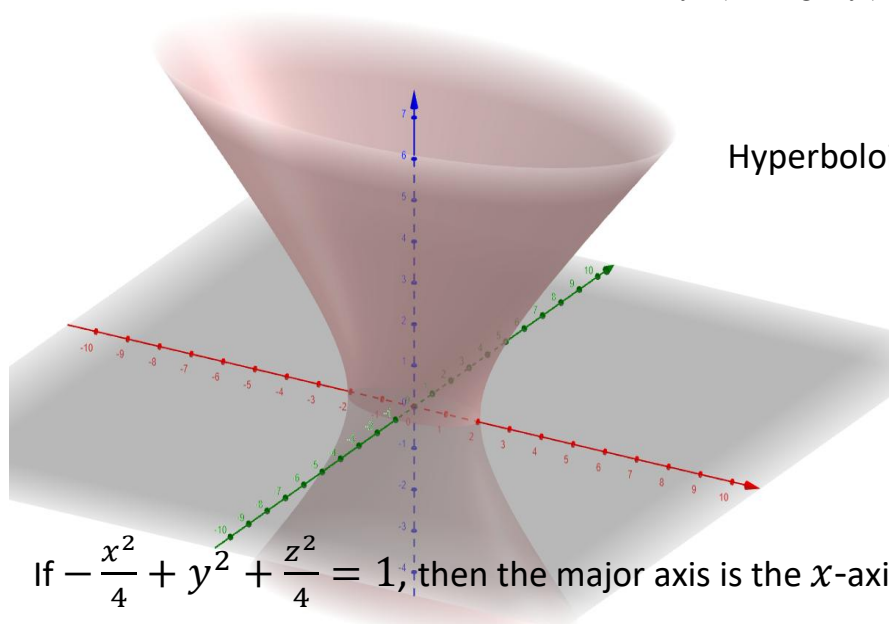
$k < -1$ or $k > 1$, major axis is z axis.

At $x = 0$: $y^2 - \frac{z^2}{4} = 1$ hyperbolas in slices $\parallel yz$ plane

At $x = k$: $y^2 - \frac{z^2}{4} = 1 - \frac{k^2}{4}$, hyperbolas in yz plane if $k \neq \pm 2$

$-2 < k < 2$, major axis is y axis

$k < -2$ or $k > 2$, major axis is z axis.



Hyperboloid of one sheet

If $-\frac{x^2}{4} + y^2 + \frac{z^2}{4} = 1$, then the major axis is the x -axis (with negative term).